An Approximate Solution of Non-Linear System of Volterra Integral Equation

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ABSTRACT

A Taylor series expansion is developed and applied to evaluate an approximate solution of the non-linear system of Volterra integral equation of the second kind for both Urysohn and Hammerstein types. The solution is based on substituting for the unknown function after differentiating both sides of the integral equation. Program associated with above methods is written in Matlab, finally, by using various examples, the accuracy of this method will be shown.

1. Introduction

Integral equations appear in many engineering and physics. Numerical methods of solution for integral equations have been largely developed in the last 20 years [3,7]. Al-Faour used Taylor series expansion to evaluate the approximate solution of linear system of integral equations for Volterra type [2].

The main purpose of this paper is to consider Taylor series expansion of non-linear system of Volterra integral equation for Urysohn (SNLUVIEs) and Hammerstein (SNLHVIEs) types of the form

\[ u_i(s) = f_i(s) + \sum_{j=1}^{n} \int_{0}^{s} K_{ij}(s,t,u_j(t))dt \quad i = 1,2,...,n \]  

(1)

\[ u_i(s) = f_i(s) + \sum_{j=1}^{n} \int_{0}^{s} K_{ij}(s,t)W(t,u_j(t))dt \quad i = 1,2,...,n \]  

(2)

where \( k_{ij}(s,t) \) and \( f_i(s) \) are known functions.
This system appears in many applications for instance: the Dirichlet-Neumann mixed boundary value problems (MBVPs) on closed surfaces in \( \mathbb{R}^3 \) based on an equivalent formulation of the MBVP as a system of two integral equations [7].

2. Basic Theorem

Taylor Theorem:

Assume that \( y(t) \in C^{N+1}[t_0,b] \) and that \( y(t) \) has a Taylor series expansion of order \( N \) about the fixed value \( t=t_k \in [t_0,b] \):

\[
y(t_k + h) = y(t_k) + hT_N(t_k, y(t_k)) + O(h^{N+1})
\]

where

\[
T_N(t_k, y(t_k)) = \sum_{j=1}^{N} \frac{y^{(j)}(t_k)}{j!} h^{j-1}
\]

and \( y^{(j)}(t) = f^{(j-1)}(t, y(t)) \) denotes the \((j-1)\)st total derivative of the function \( f \) with respect to \( t \).

Fundamental Theorem of Integral Calculus (Leibniz Generalized Formula):

\[
\frac{d}{dx} \left[ \int_{a(x)}^{b(x)} F(x, y) dy \right] = \frac{\partial F(x, y)}{\partial x} dy + F(x, \beta(x)) \frac{d\beta(x)}{dx} - F(x, \alpha(x)) \frac{d\alpha(x)}{dx}
\]

Theorem (Precision of Taylor’s Method of Order \( N \)):

Assume that \( y(t) \) is the solution to the initial value problem if \( y(t) \in C^{N+1}[t_0,b] \) and \( \{(t_k, y_k)\}_{k=0}^{M} \) is the sequence of approximations generated by Taylor’s method of order \( N \), then

\[
|e_k| = |y(t_k) - y_k| = O(h^{N+1})
\]

\[
|\epsilon_{k+1}| = |y(t_{k+1}) - y_k - hT_N(t_k, y_k)| = O(h^N)
\]

In particular, the final global error (F.G.E.) at the end of the interval will satisfy:

\[
E(y(b), h) = |y(b) - y_f| = O(h^N)
\]

3. The Existence and Uniqueness Theorem

In this section we discuss the existence and uniqueness of the solution of equation (1) and (2).
An Approximate Solution…

Definition:
Let $H$ be a Hilbert space and $T$ a bounded on $H$, $T$ is not necessary a linear operation, $T$ is said to be a contraction operator if there exists a positive constant $L < 1$ such that

$$\|Tf_1 - Tf_2\| \leq L\|f_1 - f_2\| \quad \text{for all } f_1, f_2 \text{ in } H$$

Theorem 1: (Fixed Point Theorem)
Let $T$ be a contraction operator on $H$, and if $Tf = f$ has a unique solution $f$ in $H$, then such a solution is said to be a fixed point of $T$. (see [7] for proof)

Now in operator form eq. (1) can be written as:

$$U_m - K_m(U) = F_m \quad m = 1, 2, \ldots, n \quad (5)$$

where $F_m$, $m = 1, 2, \ldots, n$ are in $H$,

$$K_m(U) = \sum_{j=1}^{n} \int_{0}^{1} K_i(s, t, u_j(t))dt$$

and $K_m$, $m = 1, 2, \ldots, n$ are bounded operators such that $\forall M_m \in \mathbb{R}^+$:

$$\|K_m(U_m) - K_m(V_m)\| \leq M_m \|U_m - V_m\| \quad m = 1, 2, \ldots, n$$

Let $M = \max (M_1, M_2, \ldots, M_n)$, then we have

$$\|K_m(U) - K_m(V)\| \leq M \|U - V\| \quad (6)$$

We can now write eq. (5) in the form:

$$T(U_m) = U_m \quad m = 1, 2, \ldots, n \quad (7)$$

where $T(U_m) = F_m + K_m(U)$, $m = 1, 2, \ldots, n$

Theorem 2:
Equation (5) has a unique solution for all $F_m$, $m = 1, 2, \ldots, n$, provided that $K_m$, $m = 1, 2, \ldots, n$ are bounded operators

4. Taylor series method for (SNLUVIEs)
Consider the following non-linear SUVIE:

$$u_i(s) = f_i(s) + \sum_{j=1}^{n} K_i(s, u_j(t))dt \quad i = 1, 2, \ldots, n \quad (8)$$

Differentiating both sides of eq. (7) 3-times with respect to s, to get
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Now, put \( s = a \) into eq. (8-11) to obtain:

5. Taylor series method for (NLSHVIE)

Consider the following non-linear SHVIE:

\[
\sum_{j=1}^{n} \left\{ s \frac{\partial^2 K_{ij}(t, t_j, x_j)}{\partial s} + K_{ij}(t, t_j, x_j) \right\} = \int_{a}^{b} W(t, u_j(t)) dt + K_{ij}(t, x) W(x, u_j(x)) \quad , \quad i = 1, 2, 3, \ldots, n
\]

Differentiating both sides of eq. (12) 3 - times with respect to \( s \), to get

\[
u'_i(s) = f'_i(s) + \sum_{j=1}^{n} \left\{ s \frac{\partial^3 K_{ij}(t, t_j, x_j)}{\partial s^3} + \frac{\partial^2 K_{ij}(t, t_j, x_j)}{\partial s^2} \right\} v_j(s)
\]

\[
u''_i(s) = f''_i(s) + \sum_{j=1}^{n} \left\{ s \frac{\partial^4 K_{ij}(t, t_j, x_j)}{\partial s^4} + \frac{\partial^3 K_{ij}(t, t_j, x_j)}{\partial s^3} \right\} v_j(s)
\]

Now, put \( s = a \) into eq. (8-11) to obtain:

\[
u_i(a) = f_i(a) \quad , \quad i = 1, 2, 3, \ldots, n
\]

\[
u'_i(a) = f'_i(a) + \sum_{j=1}^{n} K_{ij}(a, a, a, u_j(a)) \quad , \quad i = 1, 2, 3, \ldots, n
\]

\[
u''_i(a) = f''_i(a) + \sum_{j=1}^{n} \left\{ s \frac{\partial^2 K_{ij}(t, t_j, x_j)}{\partial s^2} + \frac{\partial K_{ij}(t, t_j, x_j)}{\partial s} \right\} v_j(a) \quad , \quad i = 1, 2, 3, \ldots, n
\]

5. Taylor series method for (NLSHVIE)

Consider the following non-linear SHVIE:

\[
u_i(s) = f_i(s) + \sum_{j=1}^{n} \left[ K_{ij}(t, x_j) W(t, u_j(t)) dt \right] \quad , \quad i = 1, 2, 3, \ldots, n
\]
An Approximate Solution…

Now, put $s = a$ into eqs.(12-15) to get:

\[
\begin{align*}
\frac{\partial^3 K_{ij}(s,t)}{\partial s^3} \left\{ \int_0^a \frac{\partial^2 K_{ij}(s,t)}{\partial s^2} \right. & \left. \left[ W(t, u_j(t)) dt + \frac{\partial^2 K_{ij}(s,t)}{\partial s^2} \right] \Big|_{t=a} W(s, u_j(s)) + \frac{\partial \{ \frac{\partial K_{ij}(s,t)}{\partial s} \}}{\partial s} \right\} \\
& \frac{\partial K_{ij}(s,t)}{\partial s} \left. \right|_{s=a} W(s, u_j(s)) + \frac{\partial^2 K_{ij}(s,t)}{\partial s^2} \left. \right|_{s=a} W(s, u_j(s)) \\
& + \left( \frac{\partial^2 K_{ij}(s,t)}{\partial s^2} \right) \left. \right|_{s=a} W(s, u_j(s))^{\prime \prime} + K_{ij}(s,s) W^{\prime \prime}(s, u_j(s)) \left( u_j(s) \right)^2 \\
& K_{ij}(s,s) W^{\prime \prime}(s, u_j(s)) u_j(s) \quad i = 1,2,\ldots,n \\
\end{align*}
\]

Solve the above system for the quantities $u_j'(a)$, $u_j''(a)$, and $u_j'''(a)$, $j=1,2,\ldots,n$ using forward substitution. Then these values are substituted in Taylor series eq. (3), (4) at $t = t_0$, $N = 3$, and $h = t-t_0$ to obtain the solution to order $O(s^3)$:

\[
u_j(s) = u_j(a) + u_j'(a)(s-a) + \frac{1}{2!} u_j''(a)(s-a)^2 + \frac{1}{3!} u_j'''(a)(s-a)^3, \quad j = 1,2,\ldots,n
\]

6. Numerical Results

Here we present the results of applying the Taylor series expansion discussed to three different problems.
Example 1:
Consider the following non-linear system

\[ u_1(s) = f_1 + \int_0^s (s-t)(u_2(t))^2 \, dt \]
\[ u_2(s) = f_2 + \int_0^s t e^{-2u_1(t)} \, dt \]

With the equation

\[ f_1 = \frac{1}{4} (1 - e^{2s}) \quad \text{and} \quad f_2 = -se^s + 2e^s - 1 \]

The exact solution of this problem is

\[ u_1(s) = -\frac{1}{2} s \quad \text{and} \quad u_2(s) = e^s \]

\( h = 0.1 \) using a Taylor series expansion method with grid intervals 0 < s < 1

The approximate solution of the unknown function \( u(s) \) is given as:

\[ u_1(s) = -\frac{1}{2} s \quad \text{and} \quad u_2(s) = 1 + s + \frac{1}{2!} s^2 + \frac{1}{3!} s^3 \]

A comparison of our results and exact solution gives on table (1).

<table>
<thead>
<tr>
<th>s</th>
<th>( U_1(s) )</th>
<th>( U_2(s) )</th>
</tr>
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<td>L.S.E.</td>
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</tr>
</tbody>
</table>

Table (1)

Example 2:
Given \( f_1(s) \), \( f_2(s) \), we wish to find \( \Phi_1(s) \), \( \Phi_2(s) \) so that

\[ \Phi_1(s) = f_1(s) + \int_0^s \ln |\Phi_2(t)| \, dt \]
\[ \Phi_2(s) = f_2(s) + \int_0^s t e^{\Phi_1(t)} \, dt \]

With the functions
An Approximate Solution…

\[ f_1(s) = s(1 - \frac{1}{2}s) \quad \text{and} \quad f_2(s) = -s e^s + 1 \]

The exact solution is:

\[ \Phi_1(s) = s \quad \text{and} \quad \Phi_2(s) = -e^s \]

When we apply Taylor’s method, we have the following approximate solution

\[ \Phi_1(s) = s \quad \text{and} \quad \Phi_2(s) = -1 - s - \frac{1}{2!} s^2 - \frac{1}{3!} s^3 \]

Table (2) gives a comparison of our results and exact solution

<table>
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<tr>
<th>S</th>
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<th>Exact</th>
<th>( \Phi_2(s) )</th>
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<th>Exact</th>
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</table>

Table (2)

**Example 3:**

As a third example, we study the following non-linear differential equation of the second order

\[ y' + \sin(x) \left( \frac{\cos(x)}{y} - \frac{1}{y} \right) = -1, \quad x \in (0,1), \quad y(0)=0, \quad y'(0)=1 \]

Which can be written as a system of first order non-linear differential equations

\[ y_1 = y_2 \]

\[ y_2 = \sin(x) \left( \frac{1}{y_1} - \frac{\cos(x)}{y_2} \right) - 1 \]

\[ y_1(0) = 0 \]

\[ y_2(0) = 1 \] (16)
where the exact solution of this problem is:

\[ y_1 = \sin(x) \quad \text{and} \quad y_2 = \cos(x) \]

by integrating both sides of eq.(16) over \([0, x]\), we obtained the following NLSVIEs

\[ y_1(x) = \int_0^x y_2(t) \, dt \]

\[ y_2(x) = 1 - x + \int_0^x \frac{\sin(t)}{y_1(t)} \, dt - \int_0^x \frac{\sin(t) \cos(t)}{y_2(t)} \, dt \]

Table (3) gives a comparison of our results and exact solution.

<table>
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<tr>
<th>( x )</th>
<th>( y_1(s) )</th>
<th>( y_2(s) )</th>
</tr>
</thead>
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</table>

Table (3)

7-Conclusion

Taylor series expansion method was used to evaluate an approximate solution of non-linear system of Volterra Integral Equation for both Urysohn and Hammerstein types. Three examples were considered in this context.

In practice, we conclude that:

The solution obtained by Taylor series expansion is given by a function not only at some points.

Numerical computations of Taylor’s method are simple and the convergence is satisfactory.
REFERENCES


